

MATRIX CONVERTER

VARISPEED AC

200V CLASS 5.5 kW to 45 kW 400V CLASS 5.5 kW to 160 kW



VARISPEED AC MATRIX CONVERTER YASKAWA INVERTER DRIVE TECHNOLOGY

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Experience & Innovation

For more than 90 years YASKAWA has been manufacturing and supplying mechatronic products for machine building and industrial automation.

Its standard products as well as tailormade solutions are famous and have a high reputation for outstanding quality and durability.

A leader in Inverter Drives technology

Extensive research and development has allowed YASKAWA to remain at the forefront of motion control and automation technology. This technological leadership has helped to modernise industries such as mining, steel, pulp and paper, chemical, automotive, packaging, machine tool and semiconductor.

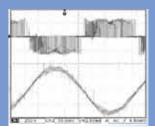
The Varispeed AC incorporates innovative technology as the world's first matrix converter to directly convert input AC voltage to output AC voltage.



The Varispeed
AC Matrix Converter
cutting-edge
features such as:

- ► High efficiency
- High performance
- Less harmonic distortion
- Powersource regeneration function
- Energy saving





Output voltage

Output current

Features & Functions

Focus on application

Variable speed applications in hospitals, schools, office buildings, and so on with strict requirements for harmonics distortion.

Lift applications with heavy repetitive loads and regenerative power.

Applications requiring regenerative power for long periods to decelerate high inertia loads to stop like centrifuges.







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Varispeed AC Advantages

High efficiency

Because of its basic construction, without use of the conventional Rectifier-DC-Bus configuration, the Matrix Converter provides the ability for regenerative power supply. The main power supply is directly switched via 9 bidirectional switching semiconductors to the motor windings.

Power source regenerative function

- The matrix converter works for motoring and regenerating without any additional equipment.
- Space saving no additional equipment for braking necessary
- Energy and cost saving the regenerative energy is fitted to the main power supply
- No heat from braking resistor

High Perfomance

- Same performance and handling as Yaskawa Varispeed 7 series
- Ecologically friendly.
- ► High dynamic and precise control
- User friendly
- Customisable
- Global specifications

Less Harmonic Distortion

- Friendly to the power supply environment
- Without any additional equipment the matrix converter keeps the input current very similar to the sinus. This helps to reduce the installed power supply and correspondence to the harmonic guideline becomes easy.



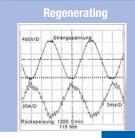


Specifications & Ratings

| Volt | age Class | | 200 |) V | | | | | 400 V | | | | |
|---------------------------------|---------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------|-------------|--------------|---------------|-----------|------------|-------------|--------------|-----------------|----------|--|
| | lel Number CIMR -ACA | 25P5 | 2011 | 2022 | 2045 | 45P5 | 4011 | 4022 | 4045 | 4075 | 4110 | 4160 | |
| | Applicable Motor Output *1 kW | 5.5 | 11 | 22 | 45 | 5.5 | 11 | 22 | 45 | 75 | 110 | 160 | |
| | Rated Input Current *2 A | | 47 | 91 | 174 | 14 | 26 | 49 | 92 | 157 | 228 | 287 | |
| | Rated Output Capacity kVA | 26 9 | 17 | 33 | 63 | 10 | 19 | 36 | 67 | 114 | 166 | 209 | |
| ut istic | Rated Output Current *3 A | 27 | 49 | 96 | 183 | 15 | 27 | 52 | 97 | 165 | 240 | 302 | |
| Output Characteristics | Max. Output Voltage | 95 % of input voltage | | | | | | | | | | 302 | |
| | Max. Output Frequency | Frequencies supported up to 120 Hz using parameter setting | | | | | | | | | | | |
| | ' ' | ed Voltage and Frequency 3-phase, 200/208/220 V, 50/60 Hz 3-phase, 380/400/415/440/460/480 V, 50/60 Hz | | | | | | | | | | | |
| ≥ ♡ | Allowable Voltage Fluctuation | +10% to | | 7220 V, 30 | 7/00 112 | J prius | 2, 300740 | 0/415/440 | 77-1007-100 | V, 30 /00 | 112 | | |
| Power Supply Characteristics | Allowable Frequency Fluctuation | | | uctuation | rate : 1 Hz | z/100 ms/ | orless) | | | | | | |
| | Allowable Power Voltage | ±370 (11C | .quericy ii | actuation | 1410 - 1 112 | 2/ 100 1113 (| 51 1033 / | | | | | | |
| | Imbalance between Phases | Within 29 | % | | | | | | | | | | |
| | Input Power Factor | 0.95 or more (When the rated load is applied.) | | | | | | | | | | | |
| | Control Method | | | | | | | | | | | | |
| | Torque Characteristics | 150% / 0 Hz (Flux vector control)*4 | | | | | | | | | | | |
| | Speed Control Range | 1: 1000 (Flux vector control)*4 | | | | | | | | | | | |
| | | 1: 1000 (Flux vector control)**4 $\pm 0.2\% \text{ (Open-loop vector control : } 25\% \pm 10\%)*4, \pm 0.05\% \text{ (Flux vector control : } 25\% \pm 10\%)*4$ | | | | | | | | | | | |
| | opeca control riccaracy | 30 Hz (Flux vector control)*4 | | | | | | | | | | | |
| | Speed Control Response | | | | | | | | | | | | |
| | Torque Limits | Provided for vector control only (4 quadrant steps can be changed by parameter settings.) | | | | | | | | | | | |
| S | Torque Accuracy | ±10% (Flux vector control : 25°C ±10°C with a vector motor, carrier frequency of 4 kHz)*4 | | | | | | | | | | | |
| Control Characteristics | Frequency Control Range | 0.01 Hz to 120 Hz | | | | | | | | | | | |
| cte | Frequency Accuracy | Digital reference : $\pm 0.01\%$ (-10% to $+40\%$), | | | | | | | | | | | |
| ara | (Temperature Characteristics) | Analog reference : ±0.1 % (25°C ±10°C) | | | | | | | | | | | |
| ਹਿ | Frequency Setting Resolution | Digital reference : 0.01 Hz, Analog reference : 0.03 Hz / 60 Hz (11 bit with no sign) | | | | | | | | | | | |
| tro | Output Frequency Resolution | 0.001 Hz | | | | | | | | | | | |
| l o | Overload Capacity *6 | 150 % of rated output current per minute (carrier frequency of 4 kHz) | | | | | | | | | | | |
| | Accel/Decel Time | 0.00 to 6000.0 s (4 selectable combinations of independent acceleration and deceleration settings) Same overload capacity for motoring and regeneration | | | | | | | | | | | |
| | Braking Torque | | | | | | | raua limit | 17 | | | | |
| | | Momentary power loss restart, Speed search, Overtorque detection, Torque limit, 17-speed control (maximum), | | | | | | | | | | | |
| | Main Control Franchisms | Accel/decel time change, S-curve accel/decel, 3-wire sequence, Autotuning (rotational or stationary), Dwell function, | | | | | | | | | | | |
| | Main Control Functions | Cooling fan ON/OFF control, Slip compensation, Torque compensation, Jump frequency, Frequency upper/lower limit | | | | | | | | | | | |
| | | settings, DC injection braking at start/stop, PID control (with sleep function), MEMOBUS communication (RS-485 /422, max. 19.2 kbps) | | | | | | | | | | | |
| | D | Fault restart, Droop control, Parameter copy, Torque control, Speed/torque control switching, etc. | | | | | | | | | | | |
| | Regenerative Function | Provided | | | | م ما سمام، ، | | | | | | | |
| | Motor Protection | | | | mal overlo | | | | | | | | |
| S | Instantaneous Overcurrent | | • • • • • • • • • • • • • • • • • • • • | | ed output | current. | | | | | | | |
| l ë | Fuse Blown Protection | | fuse blow | | | . | 6 | | i_ \ | | | | |
| l d | Overload Protection | | | | t per minu | | | - | | than EEO VA | ^ | | |
| Protective Functions | Overvoltage Protection | Stops when input power supply voltage is greater than 250 VAC. Stops when input power supply voltage is greater than 250 VAC. Stops when input power supply voltage is less than 150 VAC. Stops when input power supply voltage is less than 300 VAC. | | | | | | | | | | | |
| i. | Undervoltage Protection | | ' '' | , , | | | | | | | ما دا ماهاد د د | 2 s. *7 | |
|) tec | Momentary Power Loss | | | | rameter se | tting, oper | ation can | be continu | ed II powe | r is restore | a within | 2 5. **/ | |
| Pre | Cooling Fin Overheating | | n by therr | | | | | _ | | | | | |
| | Stall Prevention | Stall prevention during acceleration, deceleration, or running. | | | | | | | | | | | |
| | Grounding Protection *8 | | | ronic circu | | I FO 1/ | | | | | | | |
| | Charge Indicator | Remains lit until DC bus voltage falls below 50 V. | | | | | | | | | | | |
| | Ambient Operating Temperature | -10°C to +40°C (Enclosed wall -mounted type), −10°C to +45°C (Open chassis type) | | | | | | | | | | | |
| int | Ambient Operating Humidity | 95% RH max. (with no condensation) | | | | | | | | | | | |
| Environment | Storage Temperature | -20°C to +60°C (short-term temperature during transportation) | | | | | | | | | | | |
| iror | Application Site | Indoor (no corrosive gas, dust, etc.) | | | | | | | | | | | |
| -in | Altitude | 1000 m max. | | | | | | | | | | | |
| | Vibration | 10 Hz to 20 Hz : 9.8 m/s ² | | | | | | | | | | | |
| P . | | 20 Hz to 55 Hz: 5.9 m/s² (Motor output: 22 kW or less), 2.0 m/s² (Motor output: 45 kW or more). Open chassis type (IP 00) and enclosed wall -mounted type (NEMA Type 1) | | | | | | | | | | | |
| Prot | ective Structure | Open cha | issis type | (IP UU) a | na enciose | | ounted ty | | Type T) | | | | |

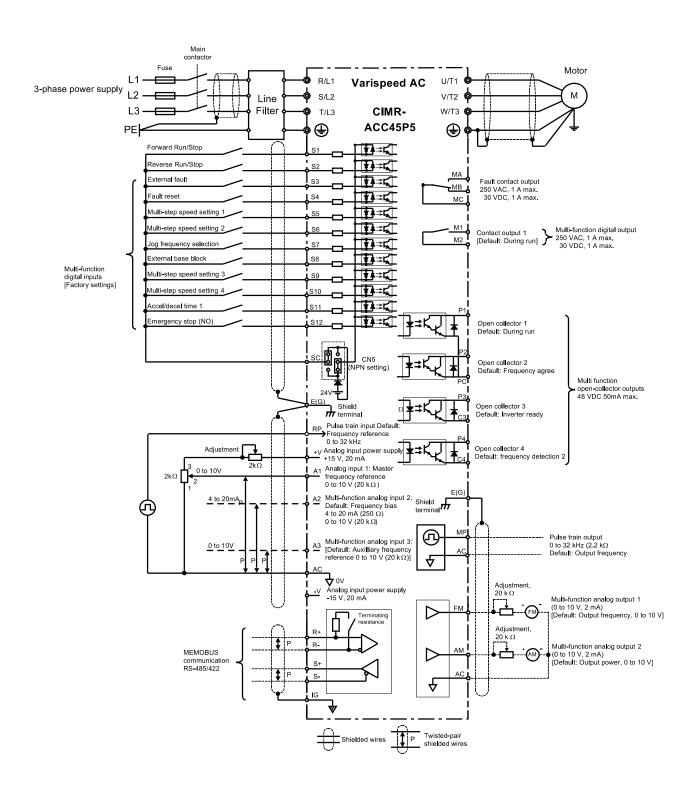
- *1: The motor capacity (kW) refers to a Yaskawa 4-pole motor. The rated output current of the MxC output amps should be equal to or greater than the motor rated current.
- *2: The rated current will vary in accordance with the values of the voltage or impedance of the power supply (including the power transformer, the input reactor, and wires).
- *3 : Required to reduce the rated output current in accordance with the values of the carrier frequencies or control method. *4 : Rotational autotuning must be performed to ensure obtaining the specifications given for open-loop or flux vector control.
- *5: The speed control accuracy depends on the installation conditions and type of motor used. Contact your Yaskawa representative for details.
- *6: Applications with repetitive loads may require derating (reducing the MxC's carrier frequency and rated current, which requires a larger frame size MxC). Contact your Yaskawa representative for details.
- *7: If the CIMR -ACA 25P5, 2011, 2022, 45P5, or 4011 needs two seconds or more to ride through momentary power loss, a back-up capacitor unit is required. If Momentary Power Loss Detection Selection (L2-01) is enabled, MxC will stop 2 ms after momentary power loss occurs. Contact your Yaskawa representative for details about use in trolley cranes and other such application that tend to experience momentary power losses or phase loss.
- *8: Protection may not be provided under the following conditions as the motor windings are grounded internally during run:
 - Low resistance to ground from the motor cable or terminal block. MxC already has a short-circuit when the power is turned on.





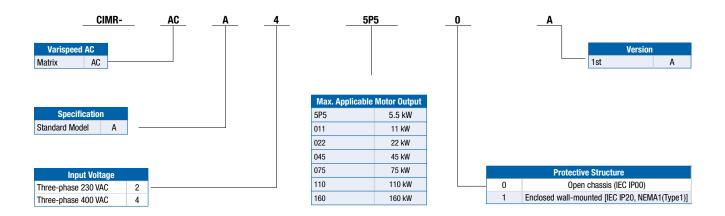


Connection Diagram

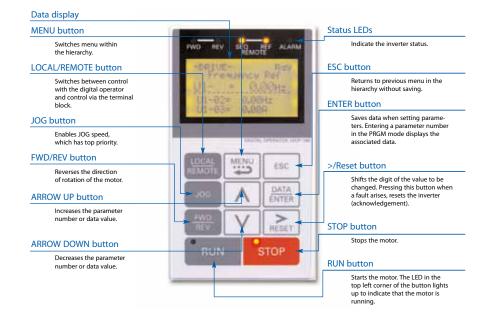


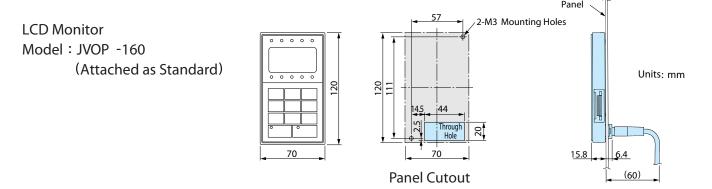


Model Code & Digital Operator

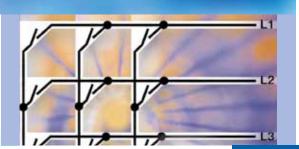


Digital Operator









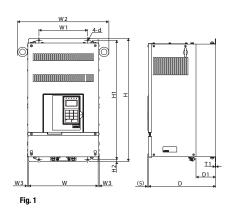
Dimensions & Options

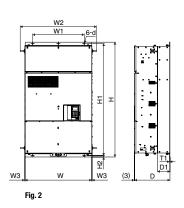
Enclosures

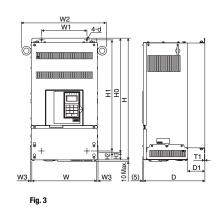
Standard Matrrix uses IP 00 design.

Open Chassis IEC IP 00 Enclosure

Enclosed Wall - Mounted (NEMA 1 IP 20)







| Voltogo Class | Drive Model | Figure | Dimensions in mm | | | | | | | | | | Ocalina |
|---------------|-------------|--------|------------------|------|-----|-----|------|-----|-----|-----|-----|-------------|------------|
| Voltage Class | | | W | Н | D | W1 | H1 | H2 | D1 | T1 | d | Weight (kg) | Cooling |
| | 2A5P50A | 1 | 300 | 530 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 28 | Fan cooled |
| | 2A0110A | | 300 | 530 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 30 | |
| | 2A0220A | | 360 | 560 | 300 | 260 | 545 | 7.5 | 130 | 2.3 | M6 | 45 | |
| Three-Phase | 2A0450A | | 480 | 865 | 403 | 310 | 841 | 12 | 170 | 4.5 | M10 | 130 | |
| 200 V Class | 2A5P51A | 3 | 300 | 564 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 30 | Fan cooled |
| | 2A0111A | | 300 | 564 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 32 | |
| | 2A0221A | | 360 | 725 | 300 | 260 | 545 | 7.5 | 130 | 2.3 | M6 | 48 | |
| | 2A0451A | | 480 | 1275 | 403 | 310 | 841 | 12 | 170 | 4.5 | M10 | 140 | |
| | 4A5P50A | 1 | 300 | 530 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 29 | Fan cooled |
| | 4A0110A | | 300 | 530 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 30 | |
| | 4A0220A | | 360 | 560 | 300 | 260 | 545 | 7.5 | 130 | 2.3 | M6 | 45 | |
| | 4A0450A | | 480 | 865 | 403 | 310 | 841 | 12 | 170 | 4.5 | M10 | 130 | |
| | 4A0750A | | 480 | 865 | 403 | 310 | 841 | 12 | 170 | 4.5 | M10 | 135 | |
| Three-Phase | 4A1100A | 2 | 695 | 1200 | 370 | 540 | 1170 | 15 | 130 | 4.5 | M12 | 230 | Fan cooled |
| 400 V class | 4A1600A | | 695 | 1200 | 370 | 540 | 1170 | 15 | 130 | 4.5 | M12 | 230 | |
| | 4A5P51A | | 300 | 290 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 31 | Fan cooled |
| | 4A0111A | | 300 | 290 | 290 | 210 | 514 | 8 | 85 | 2.3 | M6 | 32 | |
| | 4A0221A | 3 | 360 | 300 | 300 | 260 | 545 | 7.5 | 130 | 2.3 | M6 | 48 | |
| | 4A0451A | | 480 | 403 | 403 | 310 | 841 | 12 | 170 | 4.5 | M10 | 140 | |
| | 4A0751A | | 480 | 403 | 403 | 310 | 841 | 12 | 170 | 4.5 | M10 | 145 | |



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